

Adaptive Noise cancellation using Binary LMS Algorithm

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Abstract: In Speech processing Signal to Noise (SNR) Ratio plays an important role for Noise cancellation. here an attempt is made to evaluate SNR for given Noisy Speech signal using adaptive technique Binary LMS algorithm. In this proposal, Introduces the two control parameters of the Adaptive Algorithm rather than one control parameter as in case of LMS Algorithm. Also comparison is made with respect to the SNR for the given noisy speech.

Keywords: Adaptive Filters, Windows, LMS, and Binary LMS

1. INTRODUCTION

Digital filter plays an important role in digital signal processing applications. Digital filters are widely used in digital signal processing applications, such as digital signal filtering, noise filtering, signal frequency analysis, speech and audio compression, biomedical signal processing and image enhancement etc.[1]. Traditionally, most digital filter applications have been limited to audio and high-end image processing. With advances in process technologies and digital signal processing methodologies, digital filters are now cost-effective in the IF range and in almost all video markets[2]. Finite impulse response (FIR) digital filter impulse response is finite, so it can be used for Fast Fourier Transform (FFT) algorithm to achieve the filtered signal, which can greatly improve the efficiency of operation. In addition, FIR digital filter can be designed a linear phase digital filter which is convenient for image processing and data transmission applications[3]. FIR Filter banks are used to perform short-term spectrum Analysis in a variety of speech processing systems[4]. Many Window functions are widely used in digital signal processing for various applications in signal analysis and estimation, digital filter design and speech processing[5]. embedded devices. Heart rate frequency is very important health status information. The frequency measurement is used in many medical or sport applications like stress tests or life treating situation prediction.[6]. The accurate extraction of the AA signal from the ECG of AF is of great interest for subsequent analysis, since it has been documented to provide significant information on the properties of AF episodes[7]. reduction represents another important objective of ECG signal processing; in fact, the waveforms of interest are sometimes so heavily masked by noise that their presence can only be revealed once appropriate signal processing has first been applied.[8] In the last two decades, spectral analysis of the residual ECG signal (rECG, i.e. an ECG signal in which ventricular components were canceled through beat averaging techniques) has been employed to characterize atrial

activities[9]. VF is traditionally described as a system of many chaotic in the myocardium wandering, electrical wavelets, ever changing in direction and number. In contrast, recent findings indicate that stable organized centres of rapid activity, called “mother rotors”[10].

2. ADAPTIVE FILTERS & LMS ALGORITHM

Adaptive filters provide performance excellence due to their inherent pole-zero structure as compared with adaptive finite impulse response (FIR) filters that have an all-zero form, in active noise control Application[11]. RLS Filters[12]. Adaptive Filters are highly stable and effectively attenuate and often cancel disturbances[13]. An Adaptive filters are successfully used in bio-medical processing systems like Denoising of ECG Waveforms[14]. Adaptive filters play an important role in modern Digital signal processing products in area such as telephone echo cancellations, noise cancellation, equalization of communications channels, biomedical signal enhancement, active noise control, and adaptive control systems[15] and many Authors are worked out on FIR Filters using different Transform techniques[16] to [20]

3. DESIGN OF LMS BASED ADAPTIVE FILTER

In our illustrative numerical example, the adaptive filter is set to be a 100-tap FT based FIR filter to simplify numerical algebra. The filter adjustable coefficient w_n is adjusted based on the LMS algorithm.

$$w_{n+1} = w_n + m * e(n)x(n) \quad \text{--- (3)}$$

where w_n is the coefficient used currently, while w_{n+1} is the coefficient obtained from the LMS algorithm and will be used for the next coming input sample. The value of m controls the speed of the coefficient change, $e(n)$ is an error value updated each time and $x(n)$ is noised signal coefficient. The output equations of LMS algorithm leads to

$$F(n) = G(n) * x(n) \text{ --- (4)}$$

$$e(n) = d(n) - y(n) \text{ --- (5)}$$

$$G_{n+1} = G + m * e(n)x(n) \text{ ---(6)}$$

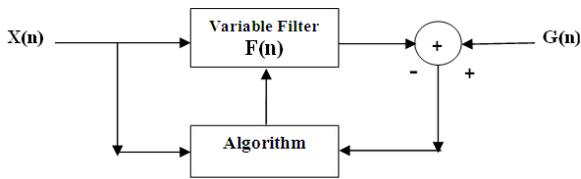


Fig1: Block diagram of Adaptive filter.

3.1 Steps to Design Adaptive Filter

1) The Low pass filter removes the corrupting low frequency noises in signal. The order of the filter is The order of the filter is 64.

Steps to low pass filter:

The desired transfer function of filter is

$$h_d(n) = \frac{\sin w_c n}{\pi n}$$

By multiplying the desired transfer function with windows designed by FrFT ,we can get transfer function of FIR band reject filter i.e

$$h(n) = h_d(n) * w(n)$$

where $w(n)$ is represents Transfer function of following windows

- 1) Rectangle window
- 2) Bartlett window
 - 3) Hanning window
 - 4) Hamming window
 - 5) Kaiser window

- 2) Now $h(n)$ is compared with $x(n)$ which produces $e(n)$.
- 3) The error coefficients are fed back to LMS algorithm to update the coefficients of FrFt based LPF.
- 4) Steps 2 and 3 repeated up to error becomes negligible.
- 5) The updated coefficients of LMS Algorithm is the the Response of desired Filter

4.DESIGN OF BINARY LMS BASED ADAPTIVE FILTER

It was Evaluated out modifications of the LMS algorithm . Getting to one of the drawbacks of LMS, that it has only one controllable parameter "mu", the selection of whose value will be the most critical from design point of view with respect to. convergence. So, Here implementation of LMS in such a way that the step-size adapts to the error occurring in each iteration.

In Binary Step-size LMS algorithm, we have two step sizes calculated from 2 values, delta and deviation. When the error increases from the previous value of error , step size is (delta deviation). And when the error decreases from its previous value, step size is (delta-deviation). And finally implemented an adaptive Filter using the BS-LMS algorithm. And Design Considerations are same as above as Discussed in Section-3.

5.RESULTS AND IMPLEMENTATIONS

The results shows responses of the FrFT based Adaptive filter with LMs Algorithm and we applied a noised signal shown in Fig2 and compares the signal to noise ratio of Noised signal before and after the filtering for different Fractional Parameters of FrFT.

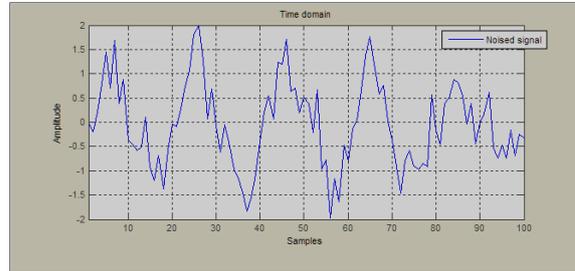


Fig2: Noised signal

When the Noised signal of fig-2 is filtered with Adaptive Filter with both LMS and Binary LMS algorithms the whole noise was removed, producing a near clean signal of fig:3 to fig:10 with different window combinations of Desired FrFt based Filter. and SNR values of noised and denoised signals are calculated for LMs and Binary LMS Algorithms for different windows are shown in Table-1

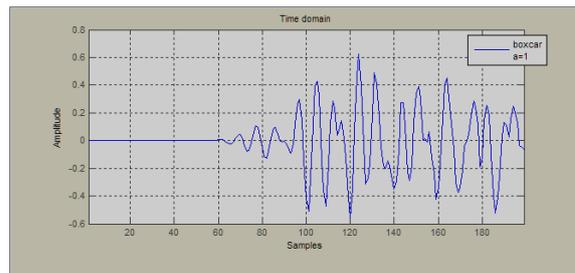


Fig3:Response of LMS based Adaptive filter with Rectangular window

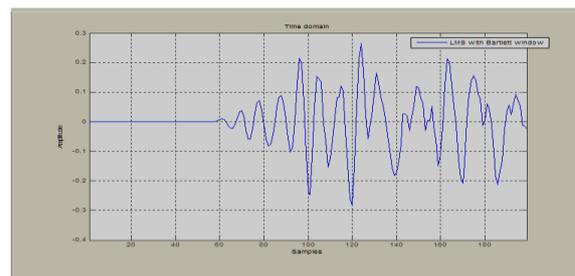


Fig4:Response of LMS based Adaptive filter with Bartlett window

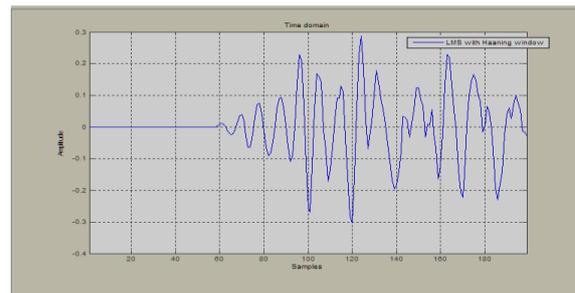


Fig5: Response of LMS based Adaptive filter with Hanning window

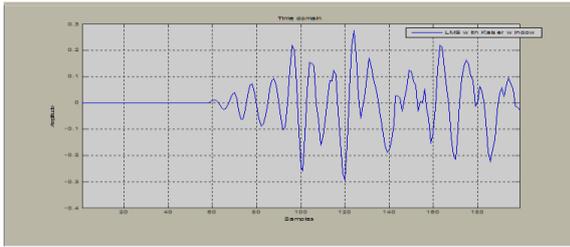


Fig6:Response of LMS based Adaptive filter with Kaiser window

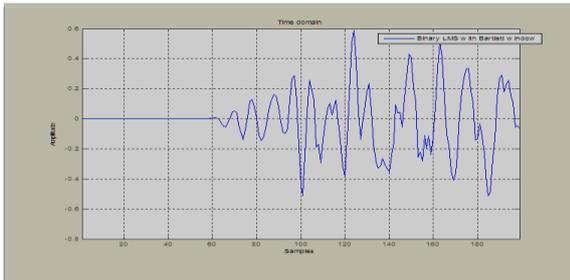


Fig7: Response of Binary LMS based Adaptive filter with Bartlett window

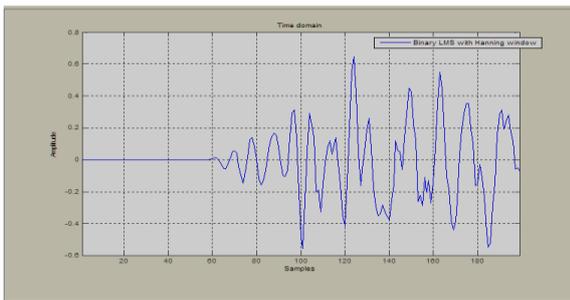


Fig8: Response of Binary LMS based Adaptive filter with Hanning window

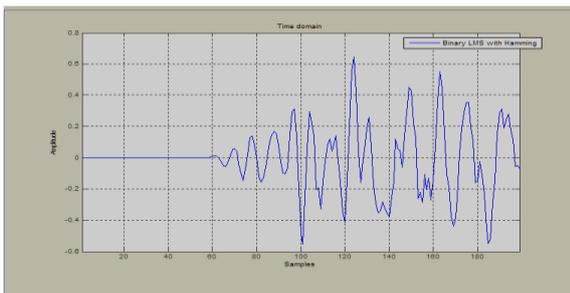


Fig9: Response of Binary LMS based Adaptive filter with Hamming window

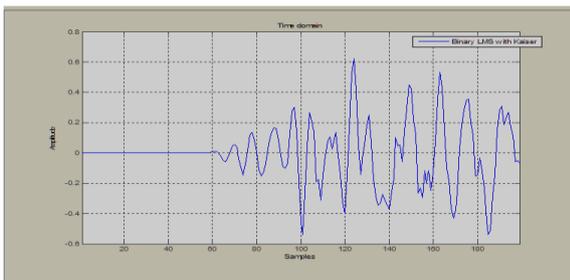


Fig10: Response of Binary LMS based Adaptive filter with Kaiser window

Table1:SNR calculation for LMS and Binary LMS for different windows

Window	SNR in DB for LMS Algorithm	SNR in dB for Binary LMS Algorithm
Rectangle	12.9576	28.2637
Bartlett	11.4899	26.7395
Hanning	12.9468	28.2315
Hamming	12.9312	28.2169
kaiser	12.4831	27.7149

6.CONCLUSION

The Implementation of Adaptive-FIR Filter using LMS Algorithm and Binary LMS Algorithm with Different Digital windows was performed. and we also applied a sample test noised signal to Adaptive filter and obtained denoised wave form at output which are shown in Fig-2 to Fig-8, and We compared SNR at input and Output for different window combinations which are shown from Table-1. From the above discussions it is concluded that Binary LMS Algorithm was given better Response in terms of SNR and Enhancement of Noise signal from noised input signal. and Binary LMS also provides fast convergence and also mean square error will also be smaller compare to LMS.

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